

### AMENDMENTS TO THE CLAIMS

1. (Currently Amended) Method of determining the velocity  $v$  and anellipticity  $\eta$  parameters for processing seismic traces obtained from seismic receivers in a common midpoint (CMP) gather including an anelliptic (Normal Move Out) NMO correction, comprising:

a preliminary step to define a plurality of nodes  $(dtn, \tau_0)$  in a CMP gather of a series of seismic traces, at least a portion of said traces corresponding to signals reflected by geological interfaces of a subsurface zone, the said nodes being indicative of parameters  $dtn$  and  $\tau_0$ , wherein dtm represent representing the NMO correction for the maximum offset and \tau\_0 represent the zero offset travel time in hyperbolic coordinates, the said preliminary step being followed by

for each node  $(dtn, \tau_0)$  defined in the preliminary step, the following steps:

for performing static NMO correction of traces in the CMP gather as a function of the values of the said parameters  $dtn, \tau_0$  at the node considered, and

for calculating the semblance function associated with the said NMO correction for the node considered; and

for each picked time  $t_0$ , a step including determination of determining the maximum semblance node  $(dtn(t_0), \tau_0(t_0))$ ,

a step to convert the  $dtn(t_0)$  and  $\tau_0(t_0)$  parameters so as to obtain the velocity  $V(t_0)$  and anellipticity anellipticity  $\eta(t_0)$  laws

and a step of processing the seismic traces in view of the obtained velocity  $V(t_0)$  and anellipticity anellipticity  $\eta(t_0)$  laws, the output of said processing used to represent the seismic traces in one or more images of at least a portion of the geological interfaces of said subsurface zone.

2. (Original) Method according to claim 1, wherein the nodes are defined during the preliminary step in an analysis volume  $(dtn, \tau_0, t_0)$  determined by minimum and maximum values respectively  $[dtn_{min}, dtn_{max}]$   $[\tau_{0min}, \tau_{0max}]$  and  $[t_{0min}, t_{0max}]$  of the  $dtn, \tau_0, t_0$  parameters.

3. (Original) Method according to claim 2, wherein, during the preliminary step, a corridor  $[dtn_{min}(t_0), dtn_{max}(t_0)]$ ,  $[\tau_{0min}(t_0), \tau_{0max}(t_0)]$  for changing  $dtn$  and  $\tau_0$  parameters is delimited inside the analysis volume as a function of plausible velocity  $V$  and anellipticity  $\eta$  values, the nodes  $(dtn, \tau_0)$  defined for applying the NMO correction being then located along the corridor thus delimited.

4. (Previously Presented) Method according to claim 1, further comprising, for each node  $(dtn, \tau_0)$ , a stacking step of the corrected seismic traces, following the semblance function calculation step.

5. (Original) Method according to claim 4, wherein the stacking of corrected traces is done using only near offset traces.

6. (Previously Presented) Method according to claim 4, further comprising for each picked time, and following the step for determining the maximum semblance node, a step of checking that values  $dtn$  and  $\tau_0$  of the maximum semblance node correspond to a stacking extreme value for the same values  $dtn$  and  $\tau_0$ .

7. (Previously Presented) Method according to claim 1, further comprising a step of selecting and adjusting the pickings obtained, following the step implemented for determining the maximum semblance node  $(dtn(t_0), \tau_0(t_0))$  for each picked time  $t_0$ , before the conversion step.

8. (Original) Method according to claim 7, wherein the said step of selecting and adjusting the pickings comprises a step of only retaining pickings  $dtn$  and  $\tau_0$  for which time to the highest semblance pickings is greater than a predefined value.

9. (Original) Method according to claim 8, wherein the said step of selecting and adjusting the pickings also comprises a step for adjusting the retained pickings  $dtn$  and  $\tau_0$  by parabolic interpolations using values about the said picked values.

10. (Original) Method according to claim 9, wherein the said step of selecting and adjusting pickings also comprises a step of eliminating retained and adjusted pickings  $dtn$  and  $\tau_0$  when it is impossible to calculate the Dix interval velocities between the picking considered and higher semblance pickings.

11. (Previously Presented) Method according to claim 1, wherein the processing applied to seismic traces is an NMO correction process implementing a static correction  $CORR_{NMO}$ .

12. (Original) Method according to claim 11, wherein, during the preliminary step, the NMO corrections  $CORR_{NMO}$  are calculated for all nodes ( $dtn$ ,  $\tau_0$ ) including in the analysis volume and all offsets of processed seismic traces.

13. (Original) Method according to claim 12, wherein the NMO correction carried out for each node ( $dtn$ ,  $\tau_0$ ), consists of applying NMO corrections  $CORR_{NMO}$  calculated during the preliminary step.

14. (Previously Presented) Method according to claim 11, wherein for a given ( $dtn$ ,  $\tau_0$ ) pair, the static NMO correction  $CORR_{NMO}$  of a seismic trace with offset  $x$  is carried out according to the following equation:

$$CORR_{NMO}(x) = -\tau_0 + \sqrt{\tau_0^2 + \frac{dtn(dtn + 2\tau_0)}{x_{max}^2}} x^2$$

in which  $X_{max}$  represents the maximum offset in the CMP gather.

15. (Withdrawn) Method according to claim 1, wherein the processing applied to seismic traces is a PSTM migration using a static NMO correction  $CORR_{PSTM}$ .

16. (Withdrawn) Method according to claim 15, wherein, during the preliminary step, the NMO corrections  $CORR_{PSTM}$  are calculated for all nodes ( $dtn$  and  $\tau_0$ ) included in the analysis volume and all migration offsets inside the migration aperture.

17. (Withdrawn) Method according to claim 16, wherein the NMO correction step carried out for each node ( $dtn$  and  $\tau_0$ ) comprises, for each offset class, application of the said NMO corrections  $CORR_{PSTM}$ , calculated during the preliminary step on all midpoints inside the migration aperture.

18. (Withdrawn) Method according to claim 17, wherein the NMO correction step carried out for each node ( $dtn$  and  $\tau_0$ ) comprises, for each offset class, the stack of the corrected midpoints following application of the said NMO corrections  $CORR_{PSTM}$ .

19 (Withdrawn) Method according to claim 15, wherein, for a given pair ( $dtn$  and  $\tau_0$ ), the static NMO correction  $CORR_{PSTM}$  is carried out according to the following equation:

$$CORR_{PSTM}(x) = -\tau_0 + \sqrt{\frac{\tau_0^2}{4} + \frac{dtn(dtn + 2\tau_0)(x - x + h)^2}{x_{max}^2}} + \sqrt{\frac{\tau_0^2}{4} + \frac{dtn(dtn + 2\tau_0)(x - x + h)^2}{x_{max}^2}}$$

where:

$x_m$  represents the coordinates of the midpoints,

$x - x_m$  represents the migration aperture PSTM,

$h$  is the half source – receiver offset,

$x_{max}$  is the maximum offset and aperture of the migration.

20. (Previously Presented) Method according to claim 14, wherein, during the final conversion step, the parameters  $dtn$  ( $t_0$ ) and ( $\tau_0$ ) are converted to the velocity law  $v(t_0)$  according to the following equation:

$$V = \frac{x_{max}}{\sqrt{dtn(dtn + 2\tau_0) \frac{t_0}{\tau_0}}}$$

21. (Currently Amended) Method according to claim 14, wherein, during the final conversion step, the parameter  $\tau_0$  ( $t_0$ ) is converted to the anellepticity anellipticity  $\eta(t_0)$  law according to

$$\eta = \frac{1}{8} \left( \frac{t_0}{\tau_0} - 1 \right)$$

22. (Currently Amended) Method according to claim 20, wherein parameter dtn is defined with respect to the velocity v and anellepticity anellipticity  $\eta$  according to the following equation:

$$dtn = \frac{8\eta}{1+8\eta} t_0 + \sqrt{\left(\frac{t_0}{1+8\eta}\right)^2 + \frac{x_{\max}^2}{(1+8\eta)V^2}}$$

23. (Currently Amended) Method according to claim 21, wherein parameter  $\tau_0$  is defined according to anellepticity anellipticity  $\eta$  according to the following equation:

$$\tau_0 = \frac{t_0}{1+8\eta}$$

24. (Withdrawn) Method of characterizing a velocity field for processing seismic data using a gather of seismic traces at common midpoint, wherein, for each travel time  $t_0$  for a zero offset, a set of parameters dtn and  $\tau_0$  is defined, representing the NMO correction for maximum offset, and the zero offset travel time respectively, in hyperbolic coordinates.

25. (Original) Method according to claim 2, further comprising, for each node (dtn,  $\tau_0$ ), a stacking step of the corrected seismic traces, following the semblance function calculation step.

26. (Original) Method according to claim 25, wherein the stacking of corrected traces is done using only near offset traces.

27. (Original) Method according to claim 25, further comprising for each picked time, and following the step for determining the maximum semblance node, a step of checking that values dtn and  $\tau_0$  of the maximum semblance node correspond to a stacking extreme value for the same values dtn and  $\tau_0$ .

28. (Original) Method according to claim 2, further comprising a step of selecting and adjusting the pickings obtained, following the step implemented for determining the maximum semblance node (dtn ( $t_0$ ),  $\tau_0$  ( $t_0$ ))) for each picked time  $t_0$ , before the conversion step.

29. (Original) Method according to claim 28, wherein the said step of selecting and adjusting the pickings comprises a step of only retaining pickings  $dtn$  and  $\tau_0$  for which time to the highest semblance pickings is greater than a predefined value.

30. (Original) Method according to claim 29, wherein the said step of selecting and adjusting the pickings also comprises a step for adjusting the retained pickings  $dtn$  and  $\tau_0$ , by parabolic interpolations using values about the said picked values.

31. (Original) Method according to claim 30, wherein the said step of selecting and adjusting pickings also comprises a step of eliminating retained and adjusted pickings  $dtn$  and  $\tau_0$  when it is impossible to calculate the Dix interval velocities between the picking considered and higher semblance pickings.

32. (Original) Method according to claim 2, wherein the processing applied to seismic traces is an NMO correction process implementing a static correction  $CORR_{NMO}$ .

33. (Original) Method according to claim 32, wherein, during the preliminary step, the NMO corrections  $CORR_{NMO}$  are calculated for all nodes ( $dtn$ ,  $\tau_0$ ) including in the analysis volume and all offsets of processed seismic traces.

34. (Original) Method according to claim 32, wherein the NMO correction carried out for each node ( $dtn$ ,  $\tau_0$ ) consists of applying NMO corrections  $CORR_{NMO}$  calculated during the preliminary step.

35. (Original) Method according to claim 32, wherein for a given ( $dtn$ ,  $\tau_0$ ) pair, the static NMO correction  $CORR_{NMO}$  of a seismic trace with offset  $x$  is carried out according to the following equation:

$$CORR_{NMO}(x) = -\tau_0 + \sqrt{\tau_0^2 + \frac{dtn(dtn+2\tau_0)}{X_{max}^2}x^2}$$

in which  $X_{max}$  represents the maximum offset in the CMP gather.

36. (Withdrawn) Method according to claim 2, wherein the processing applied to seismic traces is a PSTM migration using a static NMO correction  $CORR_{PSTM}$ .

37. (Withdrawn) Method according to claim 36, wherein, during the preliminary step, the NMO corrections CORR<sub>PSTM</sub> are calculated for all nodes (dtn and τ<sub>0</sub>) included in the analysis volume and all migration offsets inside the migration aperture.

38. (Withdrawn) Method according to claim 37, wherein the NMO correction step carried out for each node (dtn and τ<sub>0</sub>) comprises, for each offset class, application of the said NMO corrections CORR<sub>PSTM</sub>, calculated during the preliminary step on all midpoints inside the migration aperture.

39. (Withdrawn) Method according to claim 38, wherein the NMO correction step carried out for each node (dtn and τ<sub>0</sub>) comprises, for each offset class, the stack of the corrected midpoints following application of the said NMO corrections CORR<sub>PSTM</sub>.

40. (Previously Presented) Method according to claim 2, wherein the processing applied to seismic traces is a PSTM migration using a static NMO correction CORR<sub>PSTM</sub>, and wherein, for a given pair (dtn and τ<sub>0</sub>), the static NMO correction CORR<sub>PSTM</sub> is carried out according to the following equation:

$$CORR_{PSTM}(x) = -\tau_0 + \sqrt{\frac{\tau_0^2}{4} + \frac{dtn(dtn + 2\tau_0)(x - x + h)^2}{x_{max}^2}} + \sqrt{\frac{\tau_0^2}{4} + \frac{dtn(dtn + 2\tau_0)(x - x + h)^2}{x_{max}^2}}$$

where:

x<sub>m</sub> represents the coordinates of the midpoints,

x- x<sub>m</sub> represents the migration aperture PSTM,

h is the half source – receiver offset,

x<sub>max</sub> is the maximum offset and aperture of the migration.

41. (Original) Method according to claim 35, wherein, during the final conversion step, the parameters dtn (t<sub>0</sub>) and (τ<sub>0</sub>) are converted to the velocity law v (t<sub>0</sub>) according to the following equation:

$$V = -\frac{x_{max}}{\sqrt{dtn(dtn + 2\tau_0)\frac{t_0}{\tau_0}}}$$

42. (Currently Amended) Method according to claim 35, wherein, during the final conversion step, the parameter  $\tau_0$  ( $t_0$ ) is converted to the anellepticity anellipticity  $\eta$  ( $t_0$ ) law according to

$$\eta = \frac{1}{8} \left( \frac{t_0}{\tau_0} - 1 \right)$$

43. (Currently Amended) Method according to claim 41, wherein parameter  $dtn$  is defined with respect to the velocity  $v$  and anellepticity anellipticity  $\eta$  according to the following equation:

$$dtn = \frac{8\eta}{1+8\eta} t_0 + \sqrt{\left( \frac{t_0}{1+8\eta} \right)^2 + \frac{x_{\max}^2}{(1+8\eta)V^2}}$$

44. (Currently Amended) Method according to claim 42, wherein parameter  $\tau_0$  is defined according to anellepticity anellipticity  $\eta$  according to the following equation:

$$\tau_0 = \frac{t_0}{1+8\eta}$$

45. (Original): Method according to claim 3, further comprising, for each node ( $dtn$ ,  $\tau_0$ ), a stacking step of the corrected seismic traces, following the semblance function calculation step.

46. (Original) Method according to claim 45, wherein the stacking of corrected traces is done using only near offset traces.

47. (Original) Method according to claim 45, further comprising for each picked time, and following the step for determining the maximum semblance node, a step of checking that values  $dtn$  and  $\tau_0$ ; of the maximum semblance node correspond to a stacking extreme value for the same values  $dtn$  and  $\tau_0$ .

48. (Original) Method according to claim 3, further comprising a step of selecting and adjusting the pickings obtained, following the step implemented for determining the maximum semblance node ( $dtn$  ( $t_0$ ),  $\tau_0$  ( $t_0$ )) for each picked time  $t_0$ , before the conversion step.

49. (Original) Method according to claim 48, wherein the said step of selecting and adjusting the pickings comprises a step of only retaining pickings  $dtn$  and  $\tau_0$  for which time to the highest semblance pickings is greater than a predefined value.

50. (Original) Method according to claim 49, wherein the said step of selecting and adjusting the pickings also comprises a step for adjusting the retained pickings  $dtn$  and  $\tau_0$  by parabolic interpolations using values about the said picked values.

51. (Original) Method according to claim 50, wherein the said step of selecting and adjusting pickings also comprises a step of eliminating retained and adjusted pickings  $dtn$  and  $\tau_0$  when it is impossible to calculate the Dix interval velocities between the picking considered and higher semblance pickings.